

What is Claimed Is:

- 1 1. A method for decomposition of projection data acquired by scanning a set of objects  
2 using at least two x-ray spectra, the projection data including low energy projections ( $P_L$ ) and  
3 high energy projections ( $P_H$ ), said method comprising:
  - 4 A. solving the projections  $P_L$  and  $P_H$  to determine a photoelectric line integral ( $A_p$ )  
5 component of attenuation and a Compton line integral ( $A_c$ ) component of  
6 attenuation of the set of scanned objects using multi-step fitting; and  
7 B. reconstructing a Compton image  $I_c$  and a photoelectric image  $I_p$  from  $A_c$  and  $A_p$ .
- 1 2. The method of claim 1, further including, prior to step A, performing a calibration  
2 procedure using simulated data or measured data or some combination of simulated and  
3 measured data.
- 1 3. The method of claim 1, further including, prior to step A, performing a calibration  
2 procedure, wherein said calibration procedure includes generating low energy iso-transmission  
3 contours for known values of  $P_L$  at known values of  $A_p$  and at known values of  $A_c$ .
- 1 4. The method of claim 3, wherein said calibration procedure includes, for each of said low  
2 energy iso-transmission contours, fitting  $A_p$  to a polynomial function  $g_L(A_c)$ , wherein  $g_L$  is a  
3 polynomial function that represents the shape of the contour.
- 1 5. The method of claim 4, wherein  $g_L$  includes a set of coefficients  $g_{Li}$  determined at said  
2 known values of  $P_L$  and said calibration procedure includes fitting the values of each coefficient  
3  $g_{Li}$  to a polynomial function  $h_{Li}(P_L)$ .
- 1 6. The method of claim 1, wherein said calibration procedure includes computing minimum  
2 and maximum values of  $P_H$  for each of said low-energy iso-transmission contours as a function  
3 of  $P_L$ .

- 1 7. The method of claim 6, wherein said calibration procedure includes fitting the minimum  
2 values of  $P_H$  to a polynomial function  $m_L(P_L)$ .
- 1 8. The method of claim 6, wherein said calibration procedure includes fitting the maximum  
2 values of  $P_H$  to a polynomial function  $n_L(P_L)$ .
- 1 9. The method of claim 1, wherein said calibration procedure includes generating high  
2 energy iso-transmission contours for known values of  $P_H$  at known values of the  $A_p$  and at known  
3 values of the  $A_c$ .
- 1 10. The method of claim 9, wherein said calibration procedure includes, for each of said high  
2 energy iso-transmission contours, fitting  $A_p$  to a polynomial function  $g_H(A_c)$ , wherein  $g_H$  is a  
3 polynomial function that represents the shape of the contour for a given  $P_H$ .
- 1 11. The method of claim 10, wherein said  $g_H$  includes a set of coefficient  $g_{Hi}$  determined at  
2 said known values of  $P_H$  and said calibration procedure includes fitting the values of each  
3 coefficient  $g_{Hi}$  to a polynomial function  $h_{Hi}(P_H)$ .  
4
- 5 12. The method of claim 1, wherein step A includes generating a low energy iso-transmission  
6 contour corresponding to  $P_L$  and a high energy iso-transmission contour corresponding to  $P_H$ .
- 1 13. The method of claim 12, wherein step A includes determining the values of the  $A_p$  and  $A_c$   
2 at the intersection of said low energy iso-transmission contour and the high energy iso-  
3 transmission contour.
- 1 14. The method of claim 13, wherein the intersection of the low energy iso-transmission  
2 contour and the high energy iso-transmission contour is determined by equating a first  
3 polynomial function  $g_L(A_c)$  representing said low energy iso-transmission contour, wherein  $g_L$  is  
4 a polynomial function that represents the shape of the contour of  $P_L$ , with a second polynomial

5 function  $g_H(A_c)$  representing said high energy iso-transmission contour, wherein  $g_H$  is a  
6 polynomial function that represents the shape of the contour for a given  $P_H$ .

1 15. The method of claim 12, further including computing a modified value of the input low  
2 energy projection data ( $P_{Lc}$ ) and a modified value of the input high energy projection data ( $P_{Hc}$ ),  
3 wherein each of said modified values  $P_{Lc}$  and  $P_{Hc}$  are clamped to be bounded between two  
4 values.

1 16. The method of claim 15, including representing the low energy iso-transmission contour  
2 with a polynomial function  $g_L$  and determining a set of coefficients of  $g_L$  as a function of  $P_{Lc}$ .

1 17. The method of claim 15, including representing the high energy iso-transmission contour  
2 with a polynomial function  $g_H$  and determining a set of coefficients of  $g_H$  as a function of  $P_{Hc}$ .

1 18. The method of claim 15, further including, prior to step A, generating calibration data  
2 using  $P_L$ , wherein  $P_{Lc}$  is computed by clamping the value of  $P_L$  to lie between 0 and the  
3 maximum value of  $P_L$  used to generate said calibration data.

1 19. The method of claim 15, wherein the modified value  $P_{Hc}$  is determined by clamping the  
2 value of  $P_H$  to lie between a minimum value of  $P_H$  ( $P_{Hmin}$ ) and a maximum value of  $P_H$  ( $P_{Hmax}$ ).

1 20. The method of claim 19, including determining  $P_{Hmin}$  as a function of  $P_{Lc}$  and a  
2 polynomial function  $n_L$  and determining  $P_{Hmax}$  as a function of  $P_{Lc}$  and a polynomial function  $m_L$ ,  
3 wherein  $m_L$  is a polynomial function that determines  $P_{Hmin}$  for a given value of  $P_{Lc}$  and wherein  
4  $n_L$  is a polynomial function that determines  $P_{Hmax}$  for a given value of  $P_{Lc}$ .

1 21. The method of claim 1, wherein step A includes calculating a scaled Compton line  
2 integral value ( $A_{cs}$ ) as a function of a scale factor  $s_c$  and  $A_c$  and calculating a scaled photoelectric  
3 line integral value ( $A_{ps}$ ) as a function of a scale factor  $s_p$  and  $A_{ps}$ .

1 22. The method of claim 21, wherein step B includes constructing said  $I_c$  and said  $I_p$  as a  
2 function of said  $A_{cs}$  and said  $A_{ps}$ .

1 23. The method of claim 1, further including, after step B, determining an image of a basis  
2 function  $X(I_X)$  and a basis function  $Y(I_Y)$ , by solving  $I_c$  and  $I_p$  on a pixel-by-pixel basis, wherein  
3 the basis functions  $X(I_X)$  and  $Y(I_Y)$  are functions linearly combined to determine the pixel  
4 intensities in  $I_c$  and  $I_p$ .

1 24. A method for decomposition of projection data acquired by scanning a set of objects  
2 using at least two x-ray spectra, said projection data including low energy projection data ( $P_L$ )  
3 and high energy projection data ( $P_H$ ), said method comprising:

- 4 A. performing a calibration procedure using at least some simulated data or  
5 measured data or a combination of simulated and measured data, including:
- 6 i. generating low energy iso-transmission contours for known values of  $P_L$   
7 and high energy iso-transmission contours for known values of  $P_H$ ;
  - 8 ii. generating a polynomial  $g_L$  that represents the shape of the low energy iso-  
9 transmission contour for each  $P_L$ , wherein  $g_L$  includes a set of coefficients  
10  $g_{Li}$  determined at said known values of  $P_L$ ;
  - 11 iii. generating a polynomial  $g_H$  that represents the shape of the high energy  
12 iso-transmission contour for each  $P_H$ , wherein  $g_H$  includes a set of  
13 coefficients  $g_{Hi}$  determined at said known values of  $P_H$ ;
  - 14 iv. generating polynomials  $h_L$  that represents the variation of the coefficients  
15 of the polynomial  $g_L$  as a function of  $P_L$ ;
  - 16 v. generating polynomials  $h_H$  that represents the variation of the coefficients  
17 of the polynomial  $g_H$  as a function of  $P_H$ ;
  - 18 vi. determining the minimum and maximum values of  $P_H$  for each  
19 transmission line corresponding each  $P_L$ ;
  - 20 vii. generating a polynomial  $m_H$  that represents the variation of the minimum

- 21 value of  $P_H$  as a function of  $P_L$ ; and
- 22 viii. generating a polynomial  $n_H$  that represents the variation of the maximum
- 23 value of  $P_H$  as a function of  $P_L$ ;
- 24 B. solving the projections  $P_L$  and  $P_H$  to determine a photoelectric line integral ( $A_p$ )
- 25 component of attenuation and a Compton line integral ( $A_c$ ) component of
- 26 attenuation of the set of scanned objects using a multi-step fitting procedure,
- 27 including:
- 28 i. computing the values of each coefficient  $g_{Li}$  using a polynomial function
- 29  $h_{Li}(P_L)$  and computing the values of each coefficient  $g_{Hi}$  using a
- 30 polynomial function  $h_{Hi}(P_H)$ ; and
- 31 ii. determining  $A_c$  and  $A_p$  as a function of  $P_L$  and  $P_H$ , using the coefficients of
- 32  $g_L$  and the coefficients of  $g_H$ ; and
- 33 C. reconstructing a Compton image  $I_c$  and a photoelectric image  $I_p$  from  $A_c$  and  $A_p$ .
- 1 25. The method of claim 24, further including, after step C, determining an image of a basis
- 2 function  $X(I_X)$  and a basis function  $Y(I_Y)$ , by solving image  $I_c$  and image  $I_p$  on a pixel-by-
- 3 pixel basis.
- 1 26. A system for decomposing projection data for a set of scanned objects acquired using at
- 2 least two x-ray spectra, said system comprising:
- 3 A. media for storing low energy projection data ( $P_L$ ) and high energy projection data
- 4 ( $P_H$ );
- 5 B. a decomposition module configured to determine a photoelectric line integral ( $A_p$ )
- 6 component of attenuation and a Compton line integral ( $A_c$ ) component of
- 7 attenuation for  $P_L$  and  $P_H$  using multi-step fitting; and
- 8 C. an image construction module configured to construct a Compton image ( $I_c$ ) and a
- 9 photoelectric image ( $I_p$ ) from the  $A_p$  and  $A_c$ .
- 1 27. The system of claim 26, wherein the decomposition module includes:

2 D. a calibration module configured to calibrate the decomposition module using at  
3 least some simulated data or measured data or a combination of simulated data  
4 and measured data.

1 28. The system of claim 27, wherein the calibration module is configured to generate low  
2 energy iso-transmission contours for known values of  $P_L$  at known values of  $A_p$  and at known  
3 values of  $A_c$ .

1 29. The system of claim 28, wherein the calibration module is configured, for each of said  
2 low energy iso-transmission contours, to fit  $A_p$  to a polynomial function  $g_L(A_c)$ , wherein  $g_L$  is a  
3 polynomial function that represents the shape of the contour.

1 30. The system of claim 29, wherein  $g_L$  includes a set of coefficients  $g_{Li}$  determined at said  
2 known values of  $P_L$  and the calibration module is configured to fit said set of coefficients  $g_{Li}$  to a  
3 polynomial function  $h_{Li}(P_L)$ .

4 31. The system of claim 28, wherein the calibration module is configured to compute the  
5 minimum and maximum values of  $P_H$  for each of the low-energy iso-transmission contours  
6 corresponding to  $P_L$ .

7  
1 32. The system of claim 28, wherein the calibration module is configured to fit the minimum  
2 values of  $P_H$  to a polynomial function  $m_L(P_L)$ .

1 33. The system of claim 28, wherein the calibration module is configured to fit the maximum  
2 values of  $P_H$  to a polynomial function  $n_L(P_L)$ .

1 34. The system of claim 27, wherein the calibration module is configured to generate high  
2 energy iso-transmission contours for known values of  $P_H$  at known values of  $A_p$  and at known  
3 values of  $A_c$ .

- 1 35. The system of claim 34, wherein the calibration module is configured, for each of said  
2 high energy iso-transmission contours, to fit  $A_p$  to a polynomial function of  $g_H(A_c)$ , wherein  $g_H$  is  
3 a polynomial function that represents the shape of the contour for a given  $P_H$ .
- 1 36. The system of claim 34, wherein  $g_H$  includes a set of coefficients  $g_{Hi}$  determined at said  
2 known values of  $P_H$  and the calibration module is configured to fit said set of coefficients  $g_{Hi}$  to a  
3 polynomial function  $h_{Hi}(P_H)$ .
- 1 37. The system of claim 26, wherein the decomposition module is configured to generate a  
2 low energy iso-transmission contour corresponding to  $P_L$  and a high energy iso-transmission  
3 contour corresponding to  $P_H$ .
- 1 38. The system of claim 37, wherein the decomposition module is configured to determine  
2 the values of  $A_p$  and  $A_c$  at the intersection of said low energy iso-transmission contour and the  
3 high energy iso-transmission contour.
- 1 39. The method of claim 37, wherein the decomposition module is configured to compute a  
2 modified value of the input low energy projection data ( $P_{Lc}$ ) and a modified value of the input  
3 high energy projection data ( $P_{Hc}$ ), and configured to clamp said modified values  $P_{Lc}$  and  $P_{Hc}$   
4 between two values.
- 1 40. The system of claim 39, wherein the decomposition module is configured to clamp the  
2 values of  $P_L$  to lie between 0 and the maximum value of  $P_L$  used to generate a set of calibration  
3 data and to compute the modified value  $P_{Lc}$  as a function of the clamped values of  $P_L$ .
- 1 41. The system of claim 39, wherein the decomposition module is configured to clamp  $P_{Hc}$   
2 between a minimum value of  $P_H$  ( $P_{Hmin}$ ) and a maximum value of  $P_H$  ( $P_{Hmax}$ ).

1 42. The system of claim 43, wherein the decomposition module is configured to determine  
2  $P_{Hmin}$  as a function of  $P_{Lc}$  and a polynomial  $n_L$  and to determine  $P_{Hmax}$  as a function of  $P_{Lc}$  and a  
3 polynomial  $m_L$ , wherein  $m_L$  is a polynomial function representing the coefficients of  $P_L$  for the  
4 minimum values of  $P_H$  and wherein  $n_L$  is a polynomial function representing the coefficients of  
5  $P_L$  for the maximum values of  $P_H$ .

1 43. The system of claim 26, wherein the decomposition module is configured to calculate a  
2 scaled Compton line integral value ( $A_{cs}$ ) as a function of a scale factor  $s_c$  and  $A_c$  and to calculate a  
3 scaled photoelectric line integral value ( $A_{ps}$ ) as a function of a scale factor  $s_p$  and  $A_{ps}$ .

1 44. The system of claim 45, wherein the image reconstruction module is configured to  
2 reconstruct said  $I_c$  and said  $I_p$  as a function of said  $A_{cs}$  and said  $A_{ps}$ .

1 45. The system of claim 26, wherein the image reconstruction module is configured to  
2 determine an image of a basis function  $X(I_X)$  and of a basis function  $Y(I_Y)$ , by solving  $I_c$  and  $I_p$   
3 on a pixel-by-pixel basis, wherein the basis functions  $X(I_X)$  and  $Y(I_Y)$  are functions linearly  
4 combined to determine the pixel intensities in  $I_c$  and  $I_p$ .

1 46. A system for decomposing projection data for a set of scanned objects acquired using at  
2 least two x-ray spectra, said system comprising:  
3 A. media for storing low energy projection data ( $P_L$ ) and high energy projection data  
4 ( $P_H$ );  
5 B. a calibration module configured to calibrate the decomposition module using at  
6 least some simulated data or measured data or a combination of simulated and  
7 measured data, and configured to:  
8 i. generate a low energy iso-transmission contour corresponding to  $P_L$  and a  
9 high energy iso-transmission contour corresponding to  $P_H$ ;  
10 ii. generate a polynomial  $g_L$  that represents the shape of the low energy iso-  
11 transmission contour, wherein  $g_L$  includes a set of coefficients  $g_{Li}$



- 12 determined at said known values of  $P_L$ ;
- 13       iii. generate a polynomial  $g_H$  that represents the shape of the high energy iso-
- 14 transmission contour, wherein  $g_H$  includes a set of coefficients  $g_{Hi}$
- 15 determined at said known values of  $P_H$ ;
- 16       iv. generate polynomials  $h_L$  that represents the variation of the coefficients of
- 17 the polynomial  $g_L$  as a function of  $P_L$ ;
- 18       v. generate polynomials  $h_H$  that represents the variation of the coefficients of
- 19 the polynomial  $g_H$  as a function of  $P_H$ ;
- 20       vi. determine the minimum and maximum values of  $P_H$  for each transmission
- 21 line corresponding each  $P_L$ ;
- 22       vii. generate a polynomial  $m_H$  that represents the variation of the minimum
- 23 value of  $P_H$  as a function of  $P_L$ ; and
- 24       viii. generate a polynomial  $n_H$  that represents the variation of the maximum
- 25 value of  $P_H$  as a function of  $P_L$ ;
- 26       C. a decomposition module configured to determine a photoelectric line integral ( $A_p$ )
- 27 component of attenuation and a Compton line integral ( $A_c$ ) component of
- 28 attenuation for  $P_L$  and  $P_H$  using multi-step fitting, and configured to:
- 29       i. compute the values of each coefficient  $g_{Li}$  using a polynomial function
- 30  $h_{Li}(P_L)$  and to compute the values of each coefficient  $g_{Hi}$  using a
- 31 polynomial function  $h_{Hi}(P_H)$ ; and
- 32       ii. determine  $A_c$  and  $A_p$  as a function of  $P_L$  and  $P_H$  using the coefficients of  $g_L$
- 33 and the coefficients of  $g_H$ ; and
- 34       D. an image reconstruction module configured to reconstruct a Compton image ( $I_c$ )
- 35 and a photoelectric image ( $I_p$ ) from the  $A_p$  and  $A_c$ .

1   47. The system of claim 46, wherein the image construction module is configured to

2 determine an image of a basis function  $X(I_X)$  and of a basis function  $Y(I_Y)$ , by solving image  $I_c$

3 and image  $I_p$  on a pixel-by-pixel basis.